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IN THE CLAIMS

Please amend claims 1, 7-8, 12, 16-18, and 20 as follows:

1 1. (Currently amended): A pitch dynamics device comprising:

2

3 a pinch plate, said pinch plate is movably attached to a pitching machine; and

4

5 a positioning actuator operationally connected with said pinch plate, said
6 positioning actuator positions said pinch plate effectuating control of the pitch
7 dynamics of a pitched ball from said pitching machine, ~~while maintaining said~~
8 ~~pitched ball accuracy~~, without changing said pitching machine pitching wheel
9 speed, ~~said positioning actuator positions said pinch plate in at least one of the~~
10 ~~following positions~~ by transitioning said pinch plate between:

11

12 [in] a mostly horizontal position, at a minimum distance from said
13 pitching machine pitching wheel, effectuating the throwing of said pitched
14 ball with fast-speed pitch dynamics; [or] and

15

16 [in] an angled position, slowing pitch speed by decreasing the amount of
17 pinch between said pinch plate and said pitching machine pitching wheel,
18 and moving the pitch release point to an elevated trajectory, to maintain
19 said pitched ball accuracy, effectuating the throwing of said pitched ball
20 with off-speed pitch dynamics.

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1 2. (Canceled):

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1 3. (Canceled):

2

1 4. (Original): The pitch dynamics device in accordance with claim 1, wherein said
2 positioning actuator is at least one of the following:

3

4 i) a pinch plate support leg;

5 ii) a handle;

6 iii) a handle support;

7 iv) a pinch plate support;

8 v) a knob;

9 vi) a plurality of locking pegs;

10 vii) a cam; or

11 viii) a solenoid.

12

1 5. (Original): The pitch dynamics device in accordance with claim 4, wherein said pinch
2 plate support leg further having a slot, said slot controlling the range of motion of said
3 pinch plate support leg and the positioning of said pinch plate.

4

1 6. (Original): The pitch dynamics device in accordance with claim 4, wherein said pitch
2 dynamics device includes at least two of said pinch plate support leg, a first said pinch
3 plate support leg having a slot of length approximately three-quarters of an inch, and a
4 second said pinch plate support leg having a slot of length approximately one-half of an
5 inch, said first said pinch plate support leg and said second said pinch plate support leg
6 control the positioning and angle of said pinch plate.

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1 7. (Currently amended): The pitch dynamics device in accordance with claim 1, wherein
2 said pitch dynamics device further comprises ~~comprising~~ a control system interconnect
3 with said pitch dynamics device.

1 8. (Currently amended): The pitch dynamics device in accordance with claim 7, wherein
2 said control system ~~having a microcontroller~~ further comprises:

3
4 a microcontroller; and

5
6 a position control interface[,] interconnected with said microcontroller, said
7 position control interface is operationally connected with said positioning
8 actuator, said positioning actuator is operationally connected with said pinch
9 plate, said position control interface effectuates positioning control of said pinch
10 plate by way of said positioning actuator.

11
1 9. (Original): The pitch dynamics device in accordance with claim 7, wherein said control
2 system includes a hit pitch detector.

3
1 10. (Original): The pitch dynamics device in accordance with claim 9, wherein said hit
2 pitch detector utilizes at least one of the following methods to detect whether said pitched
3 ball was hit:

- 4
5 i) acoustical detection;
6 ii) electronic detection; or
7 iii) optical detection.
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1 11. (Previously presented): The pitch dynamics device in accordance with claim 7,
2 wherein said control system effectuates a pitch routine.
3

1 12. (Currently amended): The pitch dynamics device in accordance with claim 7, wherein
2 said control system includes a hit pitch detector, said control system utilizes hit pitch
3 detection, in part, to determine whether the next said pitched ball is thrown with fast-
4 speed or off-speed pitch dynamics.
5

1 13. (Original): The pitch dynamics device in accordance with claim 7, wherein said
2 control system includes a plurality of data communication interfaces.
3

1 14. (Previously presented): The pitch dynamics device in accordance with claim 13,
2 wherein said data communication interfaces include at least one of the following:
3

- 4 i) a keypad;
- 5 ii) a touch pad;
- 6 iii) a display;
- 7 iv) an IRDA interface;
- 8 v) a plurality of general purpose input and or outputs;
- 9 vi) a wired interface;
- 10 vii) a wireless interface;
- 11 viii) an RS232 interface;
- 12 ix) an RS485 interface;
- 13 x) a USB interface;
- 14 xi) a user interface;
- 15 xii) an audio interface;
- 16 xiii) a printer interface;

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- 17 xiv) a serial communication interface;
- 18 xv) LAN;
- 19 xvi) WAN;
- 20 xvii) TCP/IP;
- 21 xviii) ETHERNET;
- 22 xix) FIREWIRE;
- 23 xx) WIRELESS APPLICATION PROTOCOL;
- 24 xxi) WI-FI;
- 25 xxii) BLUETOOTH;
- 26 xxiii) WCDMA;
- 27 xxiv) IRDA;
- 28 xxv) GSM;
- 29 xxvi) PCS;
- 30 xxvii) GPRS;
- 31 xxviii) 1XRT;
- 32 xxix) CDMA;
- 33 xxx) CDMA 2000;
- 34 xxxi) WCDMA;
- 35 xxxii) CDPD;
- 36 xxxiii) TDMA;
- 37 xxxiv) 2G type compliant;
- 38 xxxv) 2.5G type compliant;
- 39 xxxvi) 3G type compliant;
- 40 xxxvii) 4G type compliant;
- 41 xxxviii) spread spectrum;
- 42 xxxix) a single frequency transceiver;
- 43 xl) a dual frequency transceiver;

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- 44 xli) IEEE 802.11;
45 xlii) IEEE 802.11A;
46 xliii) IEEE 802.11B; or
47 xliv) IEEE 802.11G.
48

1 15. (Previously presented): The pitch dynamics device in accordance with claim 1,
2 wherein said pitch dynamics device further comprises a brush attachment interconnect
3 with said pitch dynamics device or said pitching machine.
4

1 16. (Currently amended): The pitch dynamics device in accordance with claim 7, wherein
2 said pitch dynamics device further comprises comprising: a tree light interconnected with
3 said control system.
4

1 17. (Currently amended): A method of utilizing a pitch dynamics device to change pitch
2 dynamics of pitching machine pitched balls, said method comprising:
3

4 a) loosening a pinch plate, said pinch plate being movably attached to a pitching
5 machine;
6

7 b) aligning selectively said pinch plate, by way of a positioning actuator, said
8 positioning actuator being operationally connected with said pinch plate, said
9 pinch plate effectuates control of the pitch dynamics of a pitched ball from said
10 pitching machine, ~~while maintaining said pitched ball accuracy,~~ without changing
11 said pitching machine pitching wheel speed, ~~said positioning actuator being~~
12 ~~operationally connected with said pinch plate, said pinch plate being aligned in at~~
13 ~~least one of the following positions~~ by transitioning said pinch plate between:
14

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- 15 i) ~~[ia]~~ a mostly horizontal position, at a minimum distance from said
16 pitching machine pitching wheel, causing said pitching machine to
17 throw said pitched ball with fast-speed pitch dynamics; ~~[or]~~ and
18
19 ii) ~~[ia]~~ an angled position, slowing pitch speed by decreasing the
20 amount of pinch between said pinch plate and said pitching
21 machine pitching wheel and moving the pitch release point to an
22 elevated trajectory, to maintain said pitched ball accuracy, causing
23 said pitching machine to throw said pitched ball with off-speed
24 pitch dynamics; ~~and~~
25
26 c) securing said pinch plate in preparation of throwing said pitched ball.

27

1 18. (Currently amended): A method of utilizing a pitch dynamics device effectuated
2 pitching routine to control the pitch dynamics of pitched balls, said method comprising:

3

4 a) positioning initially by way of a control system a pinch plate, said pinch plate
5 controls the pitch dynamics of a pitch to be thrown, from a pitching machine, to a
6 batter, said control system being interconnected with said pitch dynamics device;

7

8 b) throwing said pitch from said pitching machine;

9

10 c) selecting the pitch dynamics of the next said pitch based in part on a pitch
11 routine executed by said control system, or selectively based in part on operator
12 input; ~~and~~

13

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14 d) repositioning by way of said control system said pinch plate, effectuating
15 control of the pitch dynamics of the next said pitch to be thrown, from said
16 pitching machine, to said batter; and
17

18 e) returning selectively to step 'b'.
19

1 19. (Original): The method in accordance with claim 18, wherein selecting the pitch
2 dynamics in step 'c' includes selecting the pitch dynamics based in part on at least one of
3 the following:
4

- 5 i) data communication with a wireless device;
 - 6 ii) data communication with a wired device;
 - 7 iii) a preprogrammed pitch routine;
 - 8 iv) by pseudo random pitch selection;
 - 9 v) by random pitch selection; or
 - 10 vi) by utilization of a hit pitch detector.
- 11

1 20. (Currently amended): A method of utilizing a pitch dynamics device having hit pitch
2 detection to control the pitch dynamics of pitched balls, said method comprising:
3

4 a) positioning initially, by way of a control system a pinch plate, said pinch plate
5 controls the pitch dynamics of a pitch to be thrown from a pitching machine to a
6 batter, said control system is interconnected with said pitch dynamics device;
7

8 b) throwing said pitch from said pitching machine;
9

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10 c) determining if said batter hit said pitch, by way of a hit pitch detector, said hit
11 pitch detector is interconnected with said control system;

12
13 d) determining, by way of said control system, said batter performance based in
14 part on the determination made in step 'c';

15
16 e) selecting the pitch dynamics, of the next said pitch, based in part on said batter
17 performance determined in step 'd';

18
19 f) repositioning, by way of said control system, said pinch plate effectuating
20 control of the pitch dynamics of the next said pitch to be thrown from said
21 pitching machine to said batter; and

22
23 g) returning selectively to step 'b'.

24
1 21. (Previously presented): The pitch dynamics device in accordance with claim 16,
2 wherein said tree light indicates at least one of the following conditions:

- 3
4 i) said pitching machine is preparing to throw said pitched ball;
5 ii) said pitching machine has thrown said pitched ball; or
6 iii) a batter should swing at said pitched ball.

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